

# TECHNICAL MEMORANDUM

X-379

EVALUATION OF BLENDED WING-BODY COMBINATIONS WITH CURVED

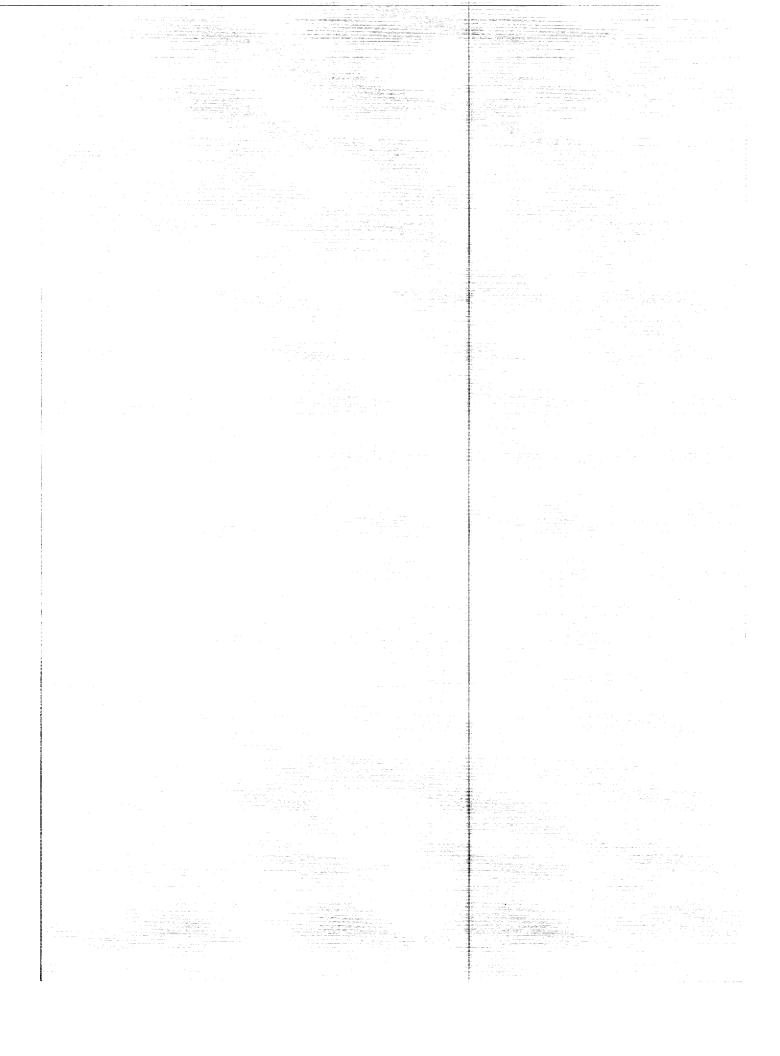
PLAN FORMS AT MACH NUMBERS UP TO 3.50

By George H. Holdaway and Jack A. Mellenthin

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#### SUMMARY

This investigation is a continuation of the experimental and theoretical evaluation of the effects of wing plan-form variations on the aerodynamic performance characteristics of blended wing-body combinations. The present report compares previously tested straight-edged delta and arrow models which have leading-edge sweeps of 59.04° and 70.82°, respectively, with related models which have plan forms with curved leading and trailing edges designed to result in the same average sweeps in each case. All the models were symmetrical, without camber, and were generally similar having the same span, length, and aspect ratios. The wing sections had an average value of maximum thickness ratio of about 4 percent of the local wing chords in a streamwise direction. The wing sections were computed by varying their shapes along with the body radii (blending process) to match the selected area distribution and the given plan form. The models were tested with transition fixed at Reynolds numbers of roughly 4,000,000 to 9,000,000, based on the mean aerodynamic chord of the wing.

The characteristic effect of the wing curvature of the delta and arrow models was an increase at subsonic and transonic speeds in the lift-curve slopes which was partially reflected in increased maximum lift-drag ratios. Curved edges were not evaluated on a diamond plan form because a preliminary investigation indicated that the curvature considered would increase the supersonic zero-lift wave drag. However, after the test program was completed, a suitable modification for the diamond plan form was discovered. The analysis presented in the appendix indicates that large reductions in the zero-lift wave drag would be obtained at supersonic Mach numbers if the leading- and trailing-edge sweeps are made to differ by indenting the trailing edge and extending the root of the leading edge.

### INTRODUCTION

The investigation reported in references 1 and 2 on evaluation of blended wing-body combinations has been extended herein to similar models with curved wing plan forms. The configurations selected were not considered to be optimum, but are useful in demonstrating design variables of possible general application. Thus the wing curvature selected for the delta and arrow models was somewhat arbitrary, but was intended to keep other variables such as aspect ratio, span, volume, and average wing sweeps unaltered. The curvature near the wing tip was roughly of the "Gothic" type described with theoretical calculations in reference 3, which indicated a possibility of reduced strength of the leading-edge vortex for moderately low angles of attack. The wing curvature evaluated was also of interest as a possible means of improving predicted and experimental wave-drag coefficients at supersonic Mach numbers at which a straight-edged plan form would have sonic or supersonic velocities normal to the wing edges.

Experiments were conducted at Mach numbers from 0.60 through 3.50 with transition fixed at Reynolds numbers per foot which varied from about 4,000,000 at transonic speeds to 2,000,000 at Mach numbers of 2.50 through 3.50. The symbols used in the figures are defined in appendix A.

Curved edges are not evaluated for a diamond plan form, because a preliminary investigation indicated that the curvature considered would require abrupt body or wing contouring for sonic design and thus would probably have separated flow drag and increased zero-lift wave drag at supersonic speeds. Another method of modifying the edges, which appears advantageous for a diamond plan form, is discussed in appendix B.

#### MODELS AND TESTS

Details of the models are presented in figures 1 and 2 and in tables I through V. Although the models with the straight wing edges are completely defined in reference 2, some of the details are repeated here for ready comparison with the models with curved wing edges. The body radii are listed in table I for each model and are different for each model. Note that the delta models do not have the large bump at the rear of the body which was used for some of the tests of reference 2, and thus the delta models have less volume than the arrow models as shown by the area distributions presented in figure 3.

The wing coordinates for the four plan forms are listed in tables II through V. The wing thickness distributions for the curved plan forms are illustrated in figure 2. Similar thickness distributions for the

straight-edged plan forms are presented in reference 2, and for all cases the thicknesses were computed as described in reference 1. The wing thickness is defined by straight-line elements perpendicular to the model center line as shown by the cross sections in figure 2. Note that the arrow wings have blunt trailing edges, as suggested in reference  $\frac{1}{4}$ , to avoid wing sections with large rearward slopes. For wing sections perpendicular to the body center line, as shown in figure 2(b), the trailing-edge thicknesses of the arrow wings were half the ridge-line thickness, except near the body juncture and the model center line (y  $\sim$  0) as shown in tables IV and V. The wing sections had an average value of maximum thickness of about  $\frac{1}{4}$  percent of the local chords in a streamwise direction and the thickness ratios were greater inboard.

The curved plan forms were formed by arcs of equal radii for both the leading and trailing edges as shown in figure 1. The arcs near the leading-edge vertex of the delta model were made tangent to the body surface slope at the point of intersection of the straight-edged wing with the body. The arcs at the leading-edge vertex of the arrow model were made to have an included half-angle equal to 10°.

The models were tested at the Ames Research Center in the 14-Foot Transonic Wind Tunnel and in the 9- by 7-foot and 8- by 7-foot supersonic test sections of the Unitary Plan Wind Tunnel. Photographs of the curved models are presented in figure 4, and the arrow model with straight edges is shown in figure 5 in the test section of the 14-Foot Transonic Wind Tunnel. Transition was fixed on all models by means of a distributed roughness. The average size of the grit was 0.040 inch, and the grit was located 1.13 inches rearward of the wing leading edge (upper and lower surfaces) and 1.13 inches rearward of the body nose in a streamwise direction. This location of the grit fixed the amount of laminar flow at 5 percent of the wing area for the entire Mach number range. Selection of the grit was based on the results of references 1 and 2 which indicated that transition would be fixed for the test conditions of this report. The results of reference 2 indicated a drag coefficient penalty due to the grit of about 0.0003 above the increase in the drag coefficients due to fixing transition for the delta model at M=3.00. The drag penalty of the grit for the curved plan forms was not measured, but could be slightly greater than the above value because of the increased amount of grit due to the curved line. The arrow model shown in figure 3(b) had transition fixed; however, the grit is difficult to see (located on the white line nearest the wing leading edge).

The ranges of the test variables in each facility are shown in the following table:

Tunnel throat	Models	R/ft	М	α, deg
14-foot	Curved arrow	1,800,000	0.25	-2 to 14
	Delta Curved delta	3,500,000 to 4,000,000	0.60 to 0.80	-2 to 11
	Arrow Curved arrow	4,000,000	0.80 to 1.20	-2 to 8
9- by 7-foot	Delta	4,000,000	1.55	-3 to 5
	Curved delta	3,000,000	1.55 to 2.35	-2 to 12
8- by 7-foot	Delta Curved delta Arrow Curved arrow	3,000,000 2,000,000	3.00 2.50 to 3.50	-3 to 13 -3 to 15

Data for the arrow model with straight wing edges were obtained in the 9- by 7-foot test section and are reported in reference 2, but not in the present report because the curved arrow model was not similarly tested in that speed range.

Three-component aerodynamic forces and moments were measured and corrected by standard procedures. For the model sizes and shapes, the force corrections for blockage and buoyancy were generally found to be negligible. At all Mach numbers the drag coefficients were adjusted by equating the body base pressures to free-stream static pressures. All aerodynamic coefficients are based on the complete plan-form area of the wings of 800 square inches. The pitching-moment coefficients were computed about a longitudinal center 34.50 inches rearward from the nose of each model. This position was selected for approximately neutral longitudinal stability at moderately supersonic speeds

#### RESULTS

The basic test data for the delta and curved delta models are presented jointly in figures 6(a) through 8(d and for the arrow models in figures 9(a) through 10(d). The Mach numbers listed in the figures are accurate within the decimal places shown, except for the test of the curved arrow model at transonic speeds where the actual test Mach numbers from 0.61 to 1.16 were 0.01 higher than the values listed in figure 9 for the basic arrow model.

Figure 7(e) presents schlieren photographs of the delta model near the wing apex at subsonic and supersonic leading-edge conditions, M=1.55 and 2.35, respectively. Note that at M=2.35 where the leading-edge is theoretically supersonic the shock wave is not attached to the wing leading

edge. Similar schlieren photographs of the curved delta model are shown in figure 7(f). In the case of the curved wing, the wing shock is broken up into a series of smaller shocks, and at M=2.35 the wing shock appears to be detached in the hollow of the wing curve.

The effects of the changes in Reynolds number are illustrated for the curved delta model in figure 7(d) for M=1.55 and in figure 8(d) for M=3.00. The effects of changes in Reynolds number for the curved arrow model are illustrated in figure 10(d). The Reynolds number effects were similarly small for the straight-edged plan forms as shown in reference 2. The wing base-drag coefficients for the two arrow models are presented in figure 9(d) as a function of the lift coefficients. The variation in wing base pressures with spanwise position are presented in reference 2.

## DISCUSSION

The discussion is directed primarily toward comparing experimental data of the straight-edged and curved plan forms. The straight-edged delta and arrow models are experimentally and theoretically evaluated along with a diamond model in reference 2. The discussion of the experimental results will consider first the trends with Mach number of maximum lift-drag ratio, lift-curve slope and aerodynamic-center position; and second, the zero-lift wave-drag coefficients of the models. Theoretical wave-drag coefficients were computed for the curved delta model, so that a representative indication of the effect of wing curvature on the theoretical wave drag could be demonstrated with the delta models. All the data presented are with transition fixed and include a grit drag-coefficient penalty of at least 0.0003 (see ref. 2).

## Aerodynamic Trends with Mach Number

The basic aerodynamic parameters of the delta and curved delta models are compared in figure 11, and similar data for the arrow models are presented in figure 12. The characteristic effect of the wing curvature was an increase at subsonic and transonic speeds in the lift-curve slopes ( $\Delta C_{\rm L_{\alpha}} = 0.002$  to 0.007 per deg) which was partially reflected in increased maximum lift-drag ratios. At supersonic speeds there was little effect on these parameters as a result of wing curvature.

The wing curvature resulted in a more rearward location of the aero-dynamic center position as shown in figures 11(c) and 12(c). In general, the variation in pitching-moment coefficient with lift coefficient was more linear for the wings with curved edges than for the wings with straight edges, as may be noted in the (c) parts of figures 6 through 10.

## Zero-Lift Wave-Drag Coefficients

The effect of wing curvature on the zero-lift wave-drag coefficients is small, as may be seen in figure 13. The airfoils were sufficiently sharp that even the straight-edged plan form did not have a rise in zero-lift wave-drag coefficient at supersonic leading-edge conditions. This is more clearly shown by the comparison of experimental and theoretical (computed with the method of ref. 5 using 49 harmonics) wave-drag coefficients of the delta and curved delta models shown in figure 14. Even the theory for the delta model shown in figure 14(a) indicated negligible peaks in the wave drag at sonic leading- and trailing-edge conditions. For wings with blunter leading edges, the agreement between theory and experiment for the straight-edged plan form at supersonic leading-edge conditions would have been poor as was shown in reference 6.

### CONCLUDING REMARKS

The characteristic effect of the wing curvature investigated with delta and arrow models was an increase at subsonic and transonic speeds in the lift-curve slopes which was partially reflected in increased maximum lift-drag ratios.

Curved edges were not evaluated on a liamond plan form because a preliminary investigation indicated that the curvature considered would increase the supersonic zero-lift wave drag. However, after the test program was completed, a suitable modification for the diamond plan form was discovered. The analysis presented in the appendix indicates that large reductions in the zero-lift wave drag would be obtained at supersonic Mach numbers if the leading- and trailing-edge sweeps are made to differ by indenting the trailing edge and extending the root of the leading edge.

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National Aeronautics and Space Administration
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# APPENDIX A

# NOTATION

A	aspect ratio
Ъ	model span
${\tt C}_{{\tt D}}$	drag coefficient (All aerodynamic coefficients are based on the total wing area.)
$\mathtt{C}_{\mathtt{D}_{\mathbf{f}}}$	friction drag coefficient
$\frac{c_{D_1}}{c_{L^2}}$	slope of the curve of drag coefficient due to lift versus lift coefficient squared, taken at the lift-coefficient data point nearest that for $(L/D)_{max}$
$^{\mathrm{C}}_{\mathrm{D}_{\mathrm{O}}}$	zero-lift drag coefficient
$^{\mathrm{C}}\mathrm{D}_{wb}$	wing base drag coefficient
$\mathtt{C}_{\mathtt{L}}$	lift coefficient
$^{\mathrm{C}}\mathrm{L}_{lpha}$	lift-curve slope, per deg
$C_{\mathbf{m}}$	pitching-moment coefficient about body station 34.50 inches from the body nose measured in the conventional x direction
С	local wing chord measured in a streamwise direction
e <sub>R</sub>	center-line chord
ē	mean aerodynamic chord of the wings with straight leading and trailing edges
$\left(\frac{\underline{L}}{\underline{D}}\right)_{\text{max}}$	maximum lift-drag ratio
7	model length
М	Mach number
N	total number of harmonics used to compute $\Delta \! c_{D_O}$

R	Reynolds number
$r_b$	body base radius
$S_{\overline{W}}$	total wing area
t	wing thickness
V	total model volume
X	airfoil percent-thickness term in NACA 65(06)A00X, airfoil designation
x,y,z	conventional axes measured from the nose of the body or of the wing section
$\frac{x_1}{e_R}$	aerodynamic-center location, where $x_1$ is measured in the x direction from the leadin; edge of the wing center-line chord
α	angle of attack
β	$\sqrt{M^2-1}$
$\Delta c_{\mathrm{D}_{0}}$	zero-lift wave-drag coefficient
θ	roll angle of a cutting plane tangent to a Mach cone as measured between the Z axis and the intersection of the cutting plane with the YZ plane

# Subscripts or Abbreviations

LE	wing leading edge
TE	wing trailing edge
dia	diamond
max	maximum
mod dia	modified diamond
S.I.L.E.	sonic inboard leading edge
S.I.T.E.	sonic inboard trailing edge

- S.O.L.E. sonic outboard leading edge
- S.O.T.E. sonic outboard trailing edge

#### APPENDIX B

# ANALYSIS OF A POSSIBLE MODIFICATION TO A DIAMOND PLAN FORM

Reference 1 shows that the symmetry of the diamond plan form was an asset for the blended wing-body type of design at transonic speeds. The data of reference 2 indicated that at higher supersonic speeds the diamond, arrow, and delta plan forms were sufficiently similar in their aerodynamic characteristics that variations in zero-lift wave drag usually decided which model had the highest lift-drag ratic. The possible improvements in supersonic zero-lift wave-drag coefficients are the greatest for the blended diamond wing-body combination because the structural rigidity of the diamond plan form would permit a thinner wing, and the sonic-edge effects could be reduced by sweeping the wing in steps.

The effects of these possible improvements are illustrated in an analysis of two hypothetical models shown in figure 15. The diamond wing plan form is identical with that used for the blended wing-body investigation. The modified diamond plan form of the same aspect ratio was designed as shown in figure 15 with anticipated lift and drag-due-to-lift characteristics similar to the mean of the values for the blended diamond and delta models (which were similar, see ref. 2). A somewhat larger body (von Karman ogive to body station 60, cylinder to body station 80) was introduced to maintain the model volume, even with thinner wings, equal to or in excess of that used for the blended wing-body investigation. The wing sections considered had the general shapes illustrated in figure 16 which shows one of the thinner thickness-to-chord ratios of 2 percent. The "cycloidal" airfoil is a scaled down cycloid, and was selected because its shape could be expressed analytically and was representative of the wing section at the mean aerodynamic chord of the blended diamond wing. The other wing sections considered were scaled down versions of the NACA 65A006 sections.

Theoretical zero-lift wave-drag coefficients for the hypothetical models with various wing-section shapes and thicknesses are presented in figures 17(a) through 17(c). The theoretical computations are based on the procedures of reference 5, and answers are based on harmonic solutions involving 49 terms. The required area distributions were also machine computed. With the diamond plan form (fig. 17(a)) there was a peak in the theoretical wave-drag coefficient at the combined sonic leading-edge and sonic trailing-edge conditions (M = 1.414) even for the thinnest wing section ((t/c)\_{max} = 0.01). With the thickest "cycloidal" section computed, the peak at sonic edge conditions is beyond the scale of the figure. This thick wing, with maximum section thicknesses of 4 percent of the local chord at the model center line and 8 percent thick at the quarter-span position, was selected as a possible short take off and landing (STOL) configuration

which would have a fan in each wing panel. The results of figure 17(a) indicate that this STOL configuration with a thick wing could possibly be successful at transonic speeds, but probably would not be successful at supersonic leading-edge conditions because of the high wave drag.

The effectiveness of the modification to the diamond plan form in eliminating the peaks in the theoretical zero-lift wave-drag coefficients at sonic edge conditions is demonstrated in figure 17(b) with the same "cycloidal" sections as those used in figure 17(a). It is interesting to note in figure 17(b) that the modified diamond wing, with  $(t/c)_{max} = 0.02$  at the model center line and  $(t/c)_{max} = 0.01$  at b/4 and at the tip, has both greater volume and lower wave drag than a similar model with the thicknesses reversed with the greater thickness ratios at the wing tip. It is of course a well-known fact (see ref. 1) that for low wave drag and low wave drag increase with Mach number, the wing volume should be concentrated inboard.

The "cycloidal" sections with forward and rearward symmetry are good at transonic speeds from a wave-drag standpoint; however, a wing section with less volume near the trailing edge such as the NACA 65(06)AOOX sections would result in lower theoretical wave-drag coefficients at sonic trailing-edge conditions as shown in figure 17(c). For this figure two intermediate wing thicknesses of possible interest were introduced to cover the range of thicknesses more adequately. The 1 percent thick wing was not computed for figure 17(c), because its wave-drag coefficients would be very similar to those shown in figure 17(b) for the 1 percent thick cycloidal wing with the same plan form. Note again in figure 17(c), for two examples (one for thin wings and the other for thick wings) that the wings with the larger thickness ratios inboard not only have the greater volume but also the lower values of wave drag.

The differences between the two airfoil shapes considered were more evident in the initial computation plots of the wave-drag coefficients as a function of  $\beta$  cos  $\theta$ , as shown in figure 18 for some of the thinner wings. In this type of plot the adverse wave-drag coefficient peaks at sonic edge conditions are more evident. Figure 18 indicates that the "cycloidal" sections are generally poorer with higher wave-drag parameters and are only slightly advantageous for Mach number near 1.00 ( $\beta$  cos  $\theta$  = 0). This will be shown more clearly in subsequent figures with thicker wings.

The modified diamond plan form resulted in reductions in theoretical zero-lift wave-drag coefficients even for the thinner wing sections as shown in figure 19. The effects of the plan-form modification were of course much greater for the thicker wings as shown in figure 20 with a coarser scale. Note again in this figure that the "cycloidal" sections are better at transonic speeds.

None of the hypothetical models were optimum in any sense, but the models with thin wings and modified plan form were designed to have a continuously decreasing wave-drag coefficient with increasing Mach number similar to that obtained with elliptic wings. Theoretical zero-lift wave-drag coefficients for the hypothetical modified diamond model with several wing thicknesses are compared in figure 21 with similar values from reference 1 or 2 for the blended diamond wing-body combination. It is apparent that the thicker winged, blended wing-body combination designed for Mach number 1.00 is an efficient configuration at transonic speeds; however, the modified diamond configurations are preferred at supersonic edge conditions.

The theoretical zero-lift wave-drag coefficients for a hypothetical modified diamond model, the blended diamond model, and elliptic wings of comparable volumes are compared in figure 22 with experimental results from reference 2 for the blended diamond model. The volume is greatest for the hypothetical modified diamond model, although its wing sections are the thinnest  $((t/c)_{max} = 0.02$  at center line,  $(t/c)_{max} = 0.01$  at b/4, and  $(t/c)_{max} = 0.01$  at the tip). The possible reductions in zero-lift wave-drag coefficients are very large relative to the blended diamond wing-body combination at supersonic leading-edge conditions. For example at Mach number 2.00 (see fig. 22), the zero-lift wave-drag coefficients might be reduced to less than one-seventh of the experimental results. An increase in maximum lift-drag ratio would naturally result from such modifications; however, the effect would be less impressive than that indicated for the wave drag as shown in the following table.

Experime	Experimental results for the blended diamond wirg-body combination $\left(\frac{V^{2/3}}{S_W} = 0.112\right)$										
М	Transition	$\mathrm{c_{D_1}/c_{L^2}}$	$^{\mathrm{C}}\mathrm{D}_{\mathbf{f}}$	$\Delta c_{\mathrm{D_o}}$	(L/D) <sub>max</sub>	(R/ft)x10 <sup>-6</sup>					
2.00 <sup>a</sup> 3.00 3.00	Fixed 0.444 Fixed .730 Free .730		0.00597 .00524 .00400	0.00645 .00512 .00512	6.65 5.80 6.29 6.22	3 3 or 4 4 3					
Estir	mated results i	for the hypot	thetical modi	fred diamo	and model $\left(\frac{V}{V}\right)$	$\frac{r^{2/3}}{S_{W}} = 0.152$					
2.00 3.00 3.00 3.00	Fixed Fixed Free Free	.433 .722 .722 .722	.00597 .00490 .00429 .00429	.00085 .00065 .00065 .00065	9.21 7.90 8.36 7.51						

Read from faired data between M=1.95 and M=2.10 brag increased on the assumption that the increase in base area over that for the experimental model was not filled by engine exhaust, that is, increase in  $C_{\rm D_Q}=0.00121$ .

Note that the experimental wave-drag coefficients for the blended diamond model are of the same order of magnitude as the friction-drag coefficients; however, the wave-drag coefficients for the hypothetical model at Mach number 3.00 are of the order of magnitude of almost one-tenth of the friction-drag coefficients. Thus attempts to improve the zero-lift wave-drag coefficients over the theoretical values indicated in the prior table do not seem to be warranted for these models unless the friction-drag coefficients could be similarly reduced.

#### REFERENCES

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Curved Arrow Delta Curved mode1 delta model arrow model mode1  $\frac{\overline{x}}{0}$ Wing .375 .750 1.500 2.250 .075 .148 .258 .356 .449 .542 .623 .693 .761 .830 alone 2.250 3.000 3.750 4.500 5.250 6.000 6.750 7.500 8.250 3.150 4.000 4.800 5.600 6.400 7.200 0.311 .371 .424 .474 .522 Equivalent body (1) .569 Wing .903 .976 1.048 alone 8.800 .656 9.000 9.750 10.500 10.683 11.000 1.116 10,400 .739 1,179 10.683 1.190 1.190 1.217 11,000 12,000 13,000 14,000 15,000 16,000 16,800 18,400 11.000 12.000 13.000 14.000 15.000 16.000 17.000 18.000 1.216 1.295 1.374 1.446 .816 12,000 13.600 .890 1.099 body 1.510 15.200 .960 15,000 16,000 0.950 .994 1.026 1.057 1.035 1.026 1.089 1.119 1.149 1.178 1.206 (2) 1.590 1.598 16.800 1.026 16,800 19.200 20.000 20.800 21.600 19.000 1.578 1.543 1.490 1.447 body 21,000 23.000 24.000 1.408 23,200 1.260 1.372 24.800 1.311 (1) (1) 1.360 1.405 1.447 1.487 1.522 26.400 28.000 29.600 31.200 33.600 35.200 36.800 37.600 38.400 38.400 39.200 40.000 1.357 26.358 1.539 1.554 1.569 1.582 (1) 35.675 36.000 37.000 38.000 39.000 35.230 36.000 37.000 38.000 1.570 1.620 1.660 1.577 1.583 1.600 1.594 1.605 1.690 1.705 1.718 1.615 1.629 1.640 1.642 1.650 1.658 1.659 1.675 1.707 1.748 1.614 1.621 39.000 40.000 39.746 1.625 40.000 40.500 1.725 40.500 41.000 1.735 41.440 41.532 42.000 1.751 1.776 1.821 41.532 42.000 43.000 44.000 43.000 45.000 Blended body 45.000 46.000 Blended body 1.797 1.841 1.881 1.905 Cylinder 47.000 48.000 47.000 1.975 1.920 2.011 1.948 1.951 49.000 49,000 49.516 50.000 51.000 52.000 1.966 51.000 2.000 1,969 (1) 53.000 54.000 1.933 53.000 1.942 54.100 54.500 55.000 56.000 57.000 1.625 1.637 1.651 1.681 1.711 55.000 56.000 57.000 57.500 57.600 1.872 1.825 1.767 1.732 1.728 55.000 56.000 57.000 1.868 1.824 1.766 57.500 57.600 1.733 57.600 57.900 58.200 58.500 58.800 59.100 59.400 59.700 60.000 1.728 1.709 1.692 1.677 1.662 1.649 Equivalent body 1.637 1.629

TABLE I. - COORDINATES FOR BODIES, INCHES

¹Same as Delta Model

2von Karman ogive, l = 40,000 in.,  $r_0 = 1.625$  in.

TABLE II.- COORDINATES FOR CURVED DELTA WING, INCHES

Semithickness, ±t/2											
х	0	±2.000	±4.333	±6.667	:10.000	±13.333	±16.667				
10.683 11.000 12.000 12.000 12.000 12.000 12.000 12.000 12.000 17.000 18.000 20.000 21.000 23.000 24.000 25.000 26.358 27.000 29.500 30.500 31.500 32.500 31.500 32.500 31.500 33.500 33.500 33.500 33.500 33.500 33.500 33.500 33.500 33.500 34.500 35.500 36.500 37.500 37.500 38.500 39.500 39.500 31.500 41.500	0.920 .945 1.017 1.047 1.072 1.092 1.105 1.105 1.107 1.092 1.107 1.092 1.107 1.092 1.107 1.092 1.068 1.033 .942 .587 .583 .583 .585 .585 .585 .585 .630 .618 .627 .635 .637 .635 .637 .637 .638 .637 .638 .639 .639 .639 .639 .639 .639 .639 .639	14.968=0 .061 .298 .14.968=0 .061 .298 .14.1 .298 .31 .502 .577 .6456 .653 .632 .5574 .6553 .5584 .5574 .5584 .5584 .5584 .5584 .5584 .5584 .5584 .5885 .5886 .588	20.065=0 .131 .241 .323 .380 .418 .412 .415 .418 .415 .415 .416 .427 .434 .4450 .466 .4780 .4888 .487 .479 .4649 .489 .471 .4649 .489 .471 .4649 .480 .4888 .487 .499 .471 .4649 .480 .481 .481 .485 .487 .485 .470 .481 .481 .485 .487 .485 .470 .482 .351 .2588 .264 .163 .1074 .010 .47.623=0 .47.623=0	23.081=0 .107 .193 .264 .283 .299 .312 .351 .359 .368 .376 .394 .408 .404 .408 .404 .398 .391 .380 .377 .345 .391 .380 .377 .345 .391 .385 .391 .398 .404 .408 .409 .410 .408 .409 .410 .408 .409 .410 .408 .404 .408 .404 .408 .409 .410 .408 .409 .410 .408 .409 .410 .408 .409 .409 .409 .409 .409 .409 .409 .409	25.961=0 .040 .089 .137 .168 .181 .192 .211 .240 .250 .268 .2763 .289 .297 .298 .297 .298 .297 .298 .297 .298 .297 .258 .255 .268 .2767 .258 .2767 .258 .2767 .258 .2767 .2767 .2767 .2767 .2768 .2767	28.460=0 .025 .044 .060 .075 .087 .100 .111 .122 .132 .142 .151 .160 .167 .174 .180 .190 .190 .190 .187 .185 .181 .176 .171 .162 .150 .099 .055 .018 43.829=0	32.358=0 .003 .014 .025 .034 .043 .051 .076 .080 .083 .086 .087 .086 .087 .086 .087 .086 .087				

TABLE III. - COORDINATES FOR DELTA WING, INCHES

	Semithickness, ±t/2											
х	0	±2.000	±4.333	±6.667	±10,000	±13.333	±16.667					
8.700 9.000 9.500 10.000 11.000 11.500 12.500 13.500 14.500 15.500 15.500 16.500 17.500 18.500 17.500 18.500 19.500 21.000 22.000 22.000 23.000 24.000 24.000 25.000 27.000 28.000 27.000 28.000 27.000 28.000 27.000 28.000 27.000 28.000 27.000 28.000 27.000 28.000 27.000 28.000 27.000 28.000 27.000 28.000 27.000 28.000 27.000 28.000 29.000 29.000 31.000 33.000 33.000 33.000 34.000 34.000 35.000 37.500 38.000 49.000 41.500 41.500 41.500 42.500 44.500 46.500 47.500 48.500 48.500 48.700	0 .540 .728 .835 .955 .987 1.000 1.000 1.000 .980 .948 .822 .800 .765 .753 .723 .721 .716 .704 .707 .716 .730 .739 .742 .739 .742 .739 .742 .739 .742 .739 .744 .439 .400 .365 .332 .295 .191 .1550 .008 0	12.033=0 .123 .225 .303 .363 .447 .475 .528 .528 .528 .528 .531 .5342 .5777 .584 .584 .5777 .584 .589 .630 .648 .636 .648 .636 .648 .635 .648 .635 .5318 .447 .5730 .648 .648 .649 .648 .649 .649 .649 .649 .649 .649 .649 .649	15.922=0 .010 .066 .113 .151 .184 .272 .303 .358 .381 .400 .416 .430 .442 .454 .465 .494 .513 .528 .534 .537 .529 .518 .496 .415 .495 .495 .395 .395 .397 .395 .395 .395 .395 .395 .395 .395 .395	19.811=0 .012 .071 .119 .161 .197 .229 .300 .319 .337 .355 .374 .429 .438 .434 .427 .407 .383 .351 .335 .316 .282 .244 .209 .175 .139 .104 .069 .034 46.478=0	25.367=0 .026 .063 .096 .126 .153 .179 .204 .229 .252 .277 .288 .296 .297 .297 .259 .249 .237 .203 .166 .131 .026 .131 .026 .026	30.922=0 .002 .033 .062 .090 .115 .138 .155 .162 .166 .172 .167 .163 .158 .124 .088 .053 .018 44.256=0	.013 .025 .036 .054 .067 .075 .077 .046 .010 43.144=0					

TABLE IV. - COORDINATES FOR CURVED ARROW WING, INCHES

Semithickness, ±t/2											
У	0	±2.000	±4.333	±6.667	±10.000	±13.333	±16.567	Ridge		Trailir	
x								±t/2	±y	±t/2	<u>+y</u>
0.000	0.000										
.500	.166					•					
1.000	.330 .397					ļ				!	
2.000	.453									<b>i</b>	
2.500	.504										
3,000 3,500	.544 .588										
4.000	.620	İ				ļ					
4.500	.655		•			1					
5.000 5.500	.680										
5.750	716					ļ					
6.000	.723						1				
5.500	748 767										
7.000 7.500	.767 .787										
3.000	806										
3.855	pt. a	0.000					]	]			
9.000	.843 .873	.017				Ì					
1.000	.891	.211									
000.9	.900	.285								İ	1
.000	.917	.409									
5.000	.948	.465									
5.000	.961	.512		1							1
5.143 7.000	.955	.544	0.000		İ						
7.500	.952	.559	.100								
5.000	.946	.570	.132	ĺ							
8.500	.942	.582	.161								1
9.000 9.500	.936	.591	.214								1
0.000	.925	.608	.238								1
1.000	.918	.625	.282	0.000	Ì			-			
1.940 2.000	.914	.641	.322	.004							
3.000	.916	.660	.360	.061							
4.000	.921	.679	.396	.114						1	
5.000 6.000	.918	.691	.426	.161							
7.000	.903	704	.472	.240						1	
8.000	.894	.708	.490	.273	0.000						
8.750 9.000	.888	.710	.503	.296	.012						1
0.000	.881	.716	523	.330	.055						
1.000	.884	.726	.541	.357	.093			1			
2.000	.893	.740 .759	.562	.383	.128						
3.122	.911	.762	.588	.414	.165			0.911	0.000		
4.000	.887	.778	.607	.436	.192			.887	.509 .812		
4.500 5.000	.870		.616	.447 .458	.206 .220			.852	1.130		
5.560	1					0.000					
5.675	.826		.634	.470	.237	.004		.826	1.577		
6,000 6,293	.789	·795 1.793	.634	.473	.243	.013		1.009	1.191		
6,500	.713	.780	.637	.479	.253	.028		.785	2.146		
7.000	.652	.740	.641	.485	.263	.041		.762	2.505		
7.500	.592		.642 .641	.490	.272	.054	1	737	2.874		
8.000 8.500			.639	.493	.285	.077		.682	3.645		
9.000	.450		.636	.494	.291	.088		.654	4.039	<b>)</b> [	
9.360	1	i	1.635			.097	1	.627	4.445	1	1

TABLE IV. - COORDINATES FOR CURVED ARROW WING, INCHES - Concluded

				S	emithickn	ess, ±t/2																					
y	0	±2.000	±4.333	±6.667	±10.000	±13.333	±16.667	Ri	dge	Trail:	ing edge																
x		12.000	1=4.333	±0.007	110.000	±13.333	110.007	±t/2	±у	±t/2	±y																
39.746 40.000 40.500 41.000 41.440 41.532	0.366	0.472 .447 .398 .335 .276	0.595 .571 .520 .462 .410 .403	0.494 .494 .491 .486 .482 .483	0.298 .300 .303 .304 .304	0.102 .106 .114 .121 .126 .128		0.612 .599 .570 .538 .512 .509	4.654 4.863 5.288 5.724 6.103 6.185	0.366 .353 .332 .293 .256 .255	0.000 .244 .728 1.219 1.658 1.750																
41.779 42.000 42.063		.251	.366	.491 1.492	.314	.136		.494	6.610	.247	2.224																
42.500 43.000 43.500 44.000 44.004																			.327 .289 .252 .215 .215	.456 .415 .375 .336	.322 .332 .341 .350	.146 .156 .164 .173		.478 .462 .446 .430	7.067 7.530 8.012 8.500	.239 .231 .223 .215	2.738 3.260 3.790 4.3 <b>2</b> 8
44.239 44.500 45.000 45.489				.297 .260	.360 .371 1.383	.182 .192	0.000 .005 .013	.414 .398	8.994 9.493	.207 .199	4.874 5.429																
45.500 46.000 46.087				.224 .188 .182	.382 .343	.203 .213	.022 .031	.383 .367	10.015 10.527	.192 .184	5.993 6.566																
46.500 47.000 47.500 48.000 48.500 48.817 48.838				.102	.304 .267 .231 .196 .162	.224 .235 .247 .258 .269	.040 .048 .057 .066 .075	.351 .335 .319 .303 .287	11.048 11.555 12.058 12.550 13.032	.176 .168 .160 .152 .144	7.148 7.740 8.342 8.954 9.576																
49.000 49.516 50.000 50.500 51.000 51.470					.138	.264 .228 .195 .161 .127 .096	.084 .094 .103 .112 .122	.271 .255 .239 .223 .207	13.505 13.985 14.417 14.864 15.295	.136 .128 .120 .112 .104	10.209 10.875 11.501 12.135 12.758																
51.500 52.000 52.500 52.660						,.	.131 .141 .151 1.154	.191 .175 .159	15.719 16.138 16.538	.098 .088 .080	13.370 13.973 14.565																
53.000 53.500 54.000 54.342							.132 .102 .071 .050	.143 .128 .112	16.938 17.325 17.693	.072 .064 .056	15.148 15.722 16.286																
54.500 55.000 55.500 56.000 56.500 57.000 57.500								.096 .080 .064 .048 .032 .016	18.059 18.413 18.753 19.086 19.402 19.707 20.000	.048 .040 .032 .024 .016 .008	16.842 17.389 17.927 18.457 18.979 19.494 20.000																

1Ridge

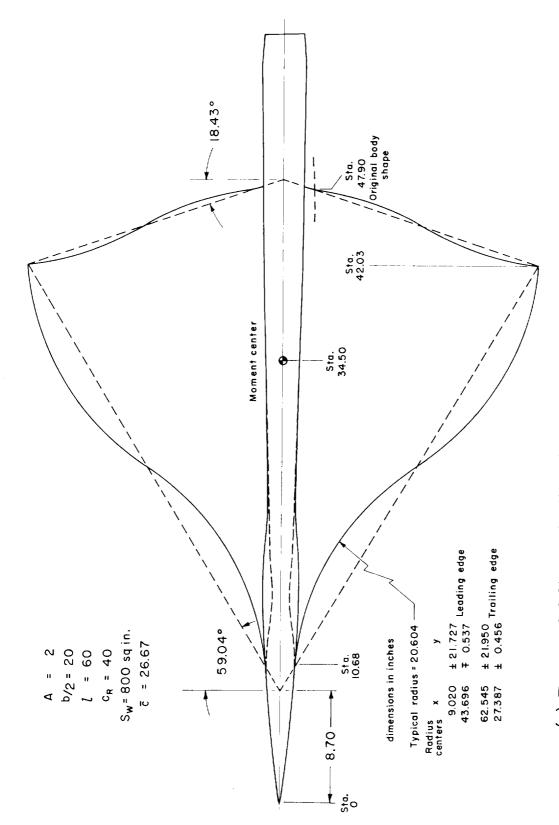
TABLE V.- COORDINATES FOR ARRCW WING, INCHES

				S	emithickn	less, ±t/2	<del></del> · <del></del> :				·
У	0	±2.000	±4.333	±6.667	±10.000	±13.333	±16.667	Ric	ige	Traili:	ng edge
x			-11000	20.001		5.555		±t/2	±y_	<b>±t</b> /2	±y
0.000 .500 1.500 2.500 3.500 4.500 5.500 5.500 5.500 6.500 7.500 8.000 9.000 11.000 12.457 13.000 14.000 12.457 13.000 14.000 17.500 18.500 19.500 19.500 20.000 21.000 22.000 23.000 24.000 25.000 26.000 27.000 28.750 29.000 31.000	0.000 .086 .171 .207 .2370 .370 .380 .380 .395 .402 .408 .414 .426 .505 .534 .5567 .587 .640 .6688 .696 .704 .718 .725 .718 .725 .718 .890 .925 .925 .932	0.000 0.0178 0.001788 0.00178 0.00178 0.00178 0.00178 0.00178 0.00178 0.001	0.000 .025 .067 .108 .148 .201 .217 .233 .247 .262 .276 .331 .362 .391 .445 .465 .508 .553 .579 .608 .617 .635 .648	0.000 .012 .030 .065 .098 .131 .164 .224 .277 .302 .327 .353 .380 .410 .437 .450	0.000 .008 .038 .067 .096 .126 .136 .155 .169			0.986 .955 .932	0.000 .552 .966		

TABLE V.- COORDINATES FOR ARROW WING, INCHES - Concluded

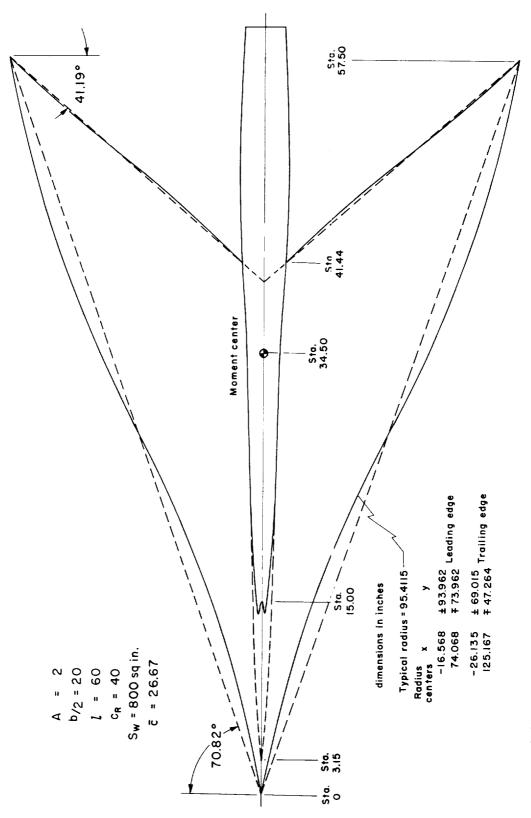
				S	emithickn	ess, ±t/2	2				
У	0	±2.000	±4.333	±6.667	±10.000	±13.333	±16.667	R1	dge	Trail	ing edge
х			- 1000		=10,000	-43.000	210.001	±t/2	±y	±t/2	±у
35.000 35.230 35.750	0.908 .898	0.853 .855 1.853	0.657 .661	0.462 .466	0.182 .188			0.905	1.379 1.570		
36.000 36.500 37.000 37.500 38.000 38.333	.852 .815 .768 .710 .642	.839 .805 .769 .725 .674	.665 .666 .668 .668	.476 .480 .486 .489 .492	.205 .215 .225 .233 .242	0.000		.838 .802 .770 .736 .703	2.207 2.621 3.034 3.448 3.862		
38.500 38.569	.576	.620	.667 1.667	.495	.250	.004		.671	4.276		
39.000 39.500 40.000 40.500 41.000 41.389	.508 .445 .387	.565 .509 .458 .397 .338	.632 .584 .540 .493 .441	.499 .499 .502 .508 .508	.258 .264 .271 .280 .285	.017 .029 .040 .052 .062		.642 .609 .582 .558 .530	4.690 5.103 5.517 5.931 6.345	0.387 .339 .300	0 .571 1.143
41.532 41.750		.268 .251	.386	.504	.295	.074		.509	6.785	.255	1.750
42.000 42.500 43.000 43.791			.350 .314 .277 .218	.468 .432 .395	.306 .318 .3 <b>2</b> 9	.085 .096 .108		.494 .478 .462	7.172 7.586 8.000	.247 .239 .231	2.286 2.857 3.429
44.000 45.000 45.417 45.833			•••	.371 .247	.352 .375 <sup>1</sup> .385	.131 .154		.430 .398	8.828 9.655	.215 .199	4.571 5.714
46.000 47.000 47.918				.100	.342 .268	.177 .200	0.000	.367 .335	10.483	.18 <b>3</b> .167	6.857 8.000
48.000 48.750					.194	.223	.002	.303	12.138	.151	9.143
49.000 49.444			e			.247 1.257	.025	.271	12.966	.136	10.286
50.000 51.000 51.667						.216 .143 .093	.048 .071	.239 .207	13.793 14.621	.120 .104	11.429 12.571
52.000 53.000 53.473						-	.094 .117 1.128	.175 .143	15.448 16.276		13.714 14.857
54.000 54.584				ļ			.090 .046	.112	17.103	.056	16.000
55.000 55.500 56.000 56.500 57.000								.080 .064 .048 .032	17.931 18.345 18.759 19.172 19.586	.032 .024 .016 .008	17.143 17.714 18.286 18.857 19.429
57.500				l				.000	20.000	.000	20.000

<sup>1</sup>Ridge



(a) The curved delta model with outline of delta model shown for comparison.

Figure 1.- Sketches of the models.



(b) The curved arrow model with the outline of the arrow model shown for comparison.

Figure 1.- Concluded.

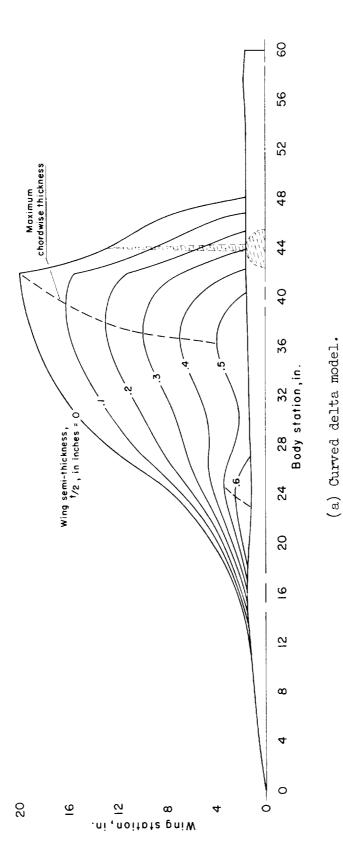
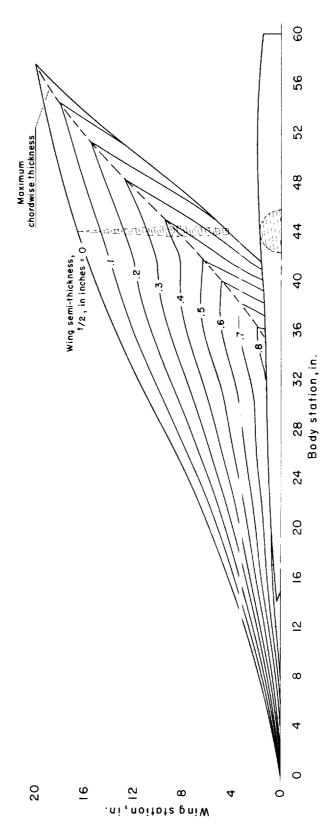


Figure 2. - Semi-plan view of the curved models with wing thickness contours.



(b) Curved arrow model.

Figure 2.- Concluded.

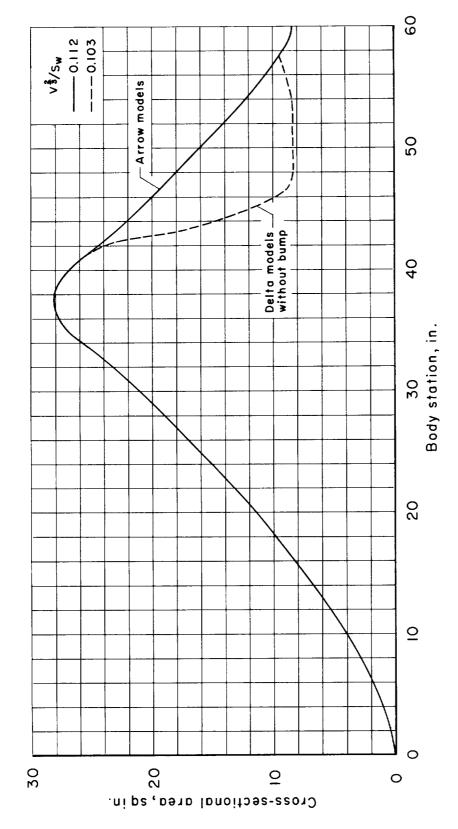


Figure 3.- The design area distribution as derived in reference 1 and modified for the delta models without the body bump.

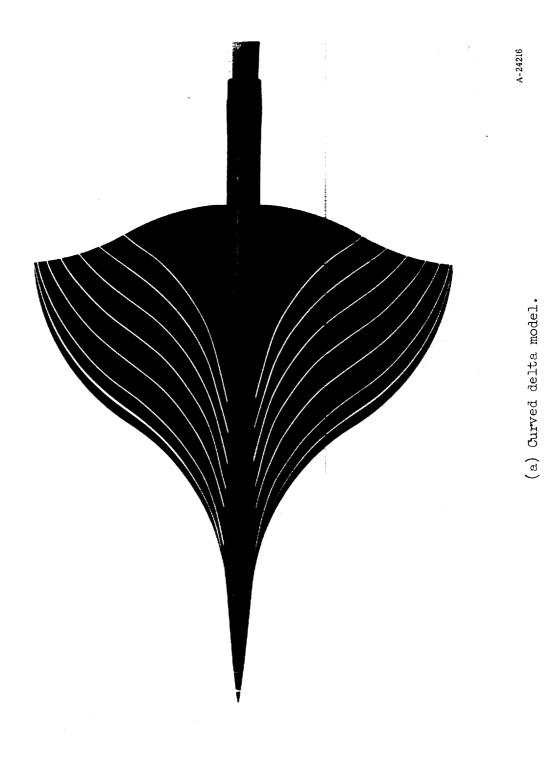


Figure 4.- Photographs of the curved models.

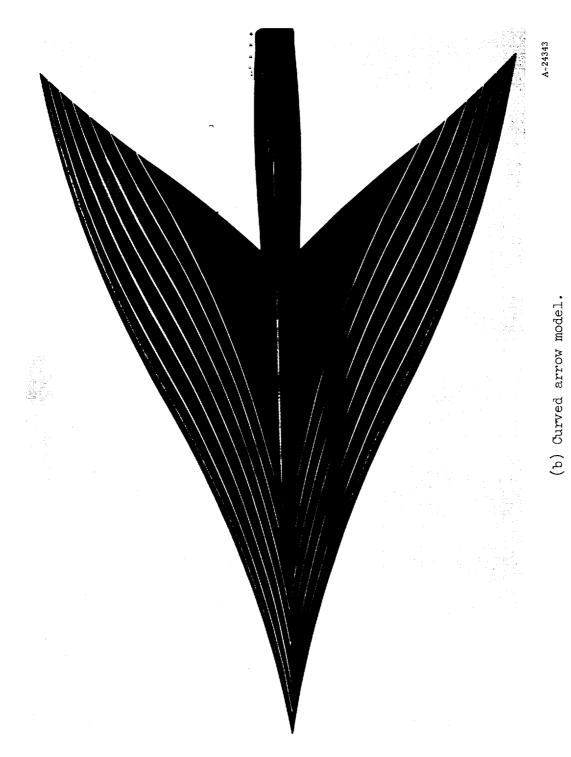


Figure 4.- Concluded.

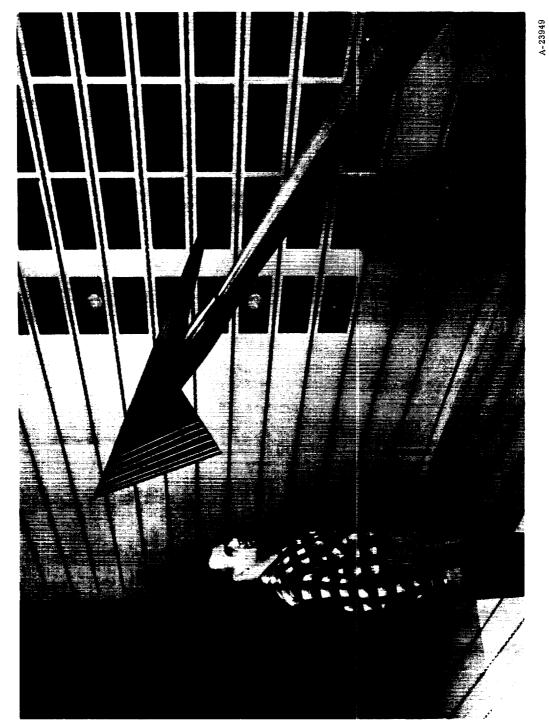


Figure 5.- Photograph of the arrow model mounted in the test section of the Ames 14-Foot Transonic Wind Tunnel.

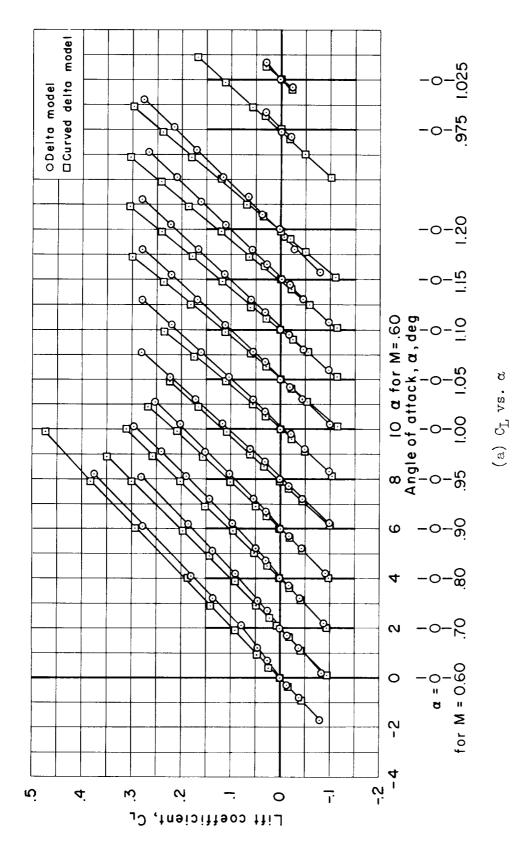
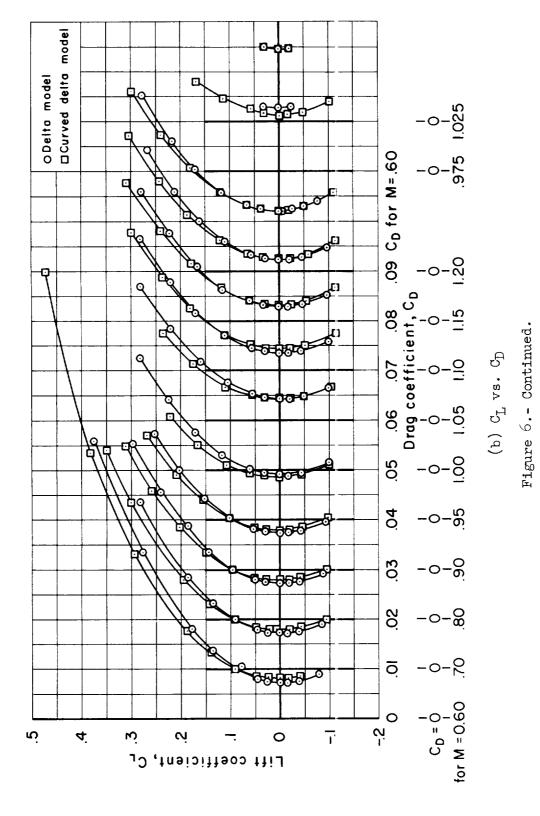
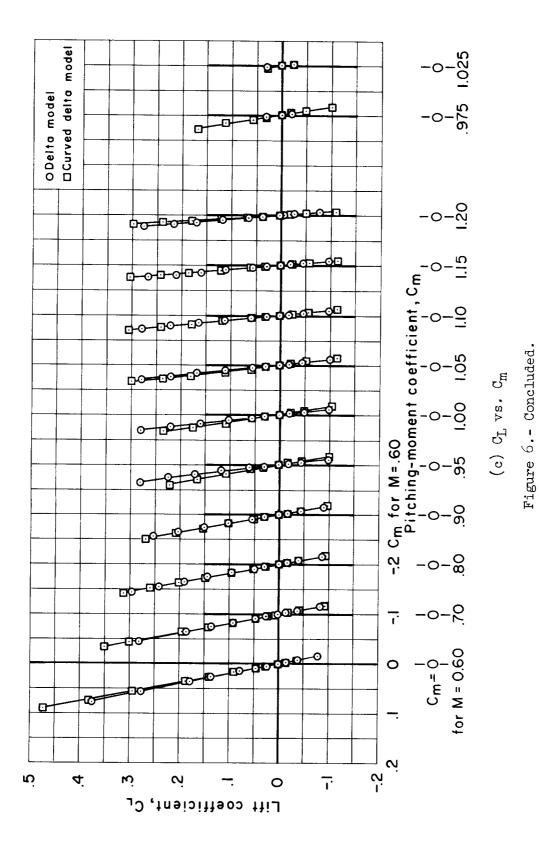


Figure 6.- Transonic aerodynamic characteristics for the delta and curved delta models (R/ft = 3,500,000 to 4,000,000).





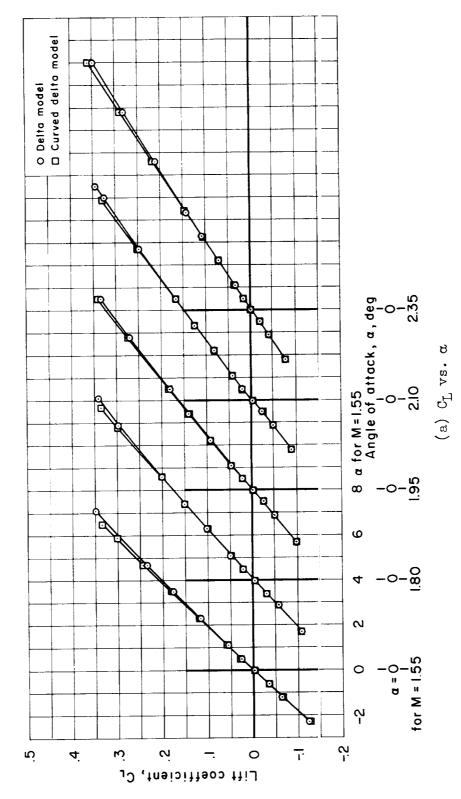
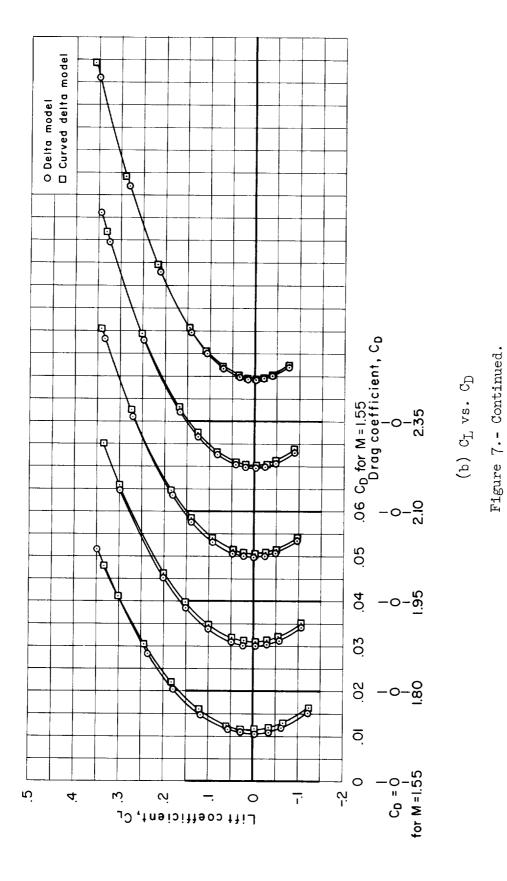
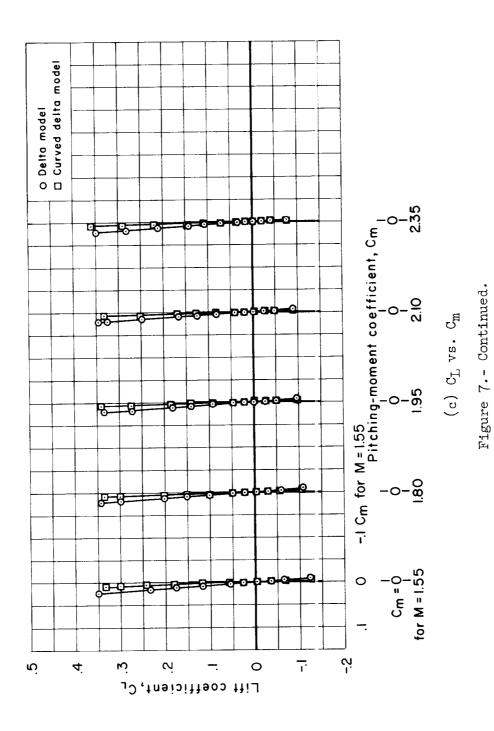


Figure 7.- Supersonic aerodynamic characteristics for the delta and curved delta models (R/ft=3,000,000).





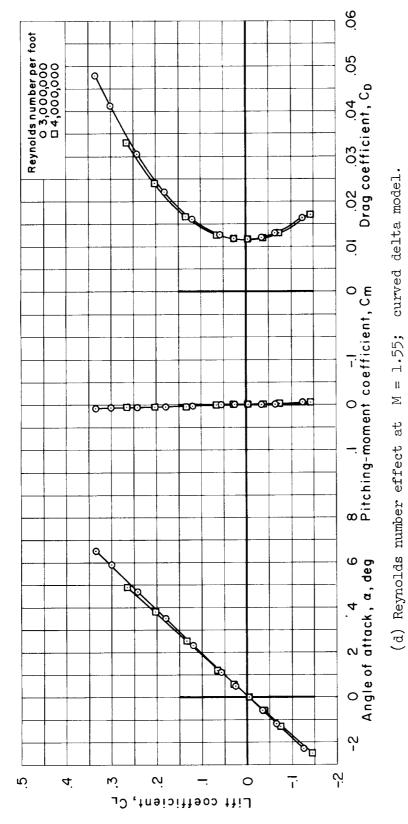


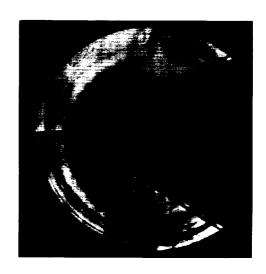
Figure 7.- Continued.

## Subsonic leading edge



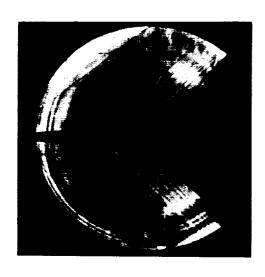
M=1.55

Supersonic leading edge

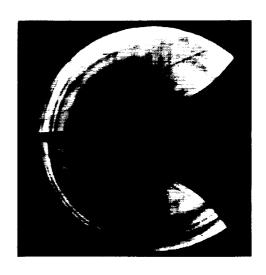


M=2.35

(e) Schlieren photographs of delta model.



M=1.55



M=2.35

(f) Schlieren photographs of curved delta model.

Figure 7.- Concluded.

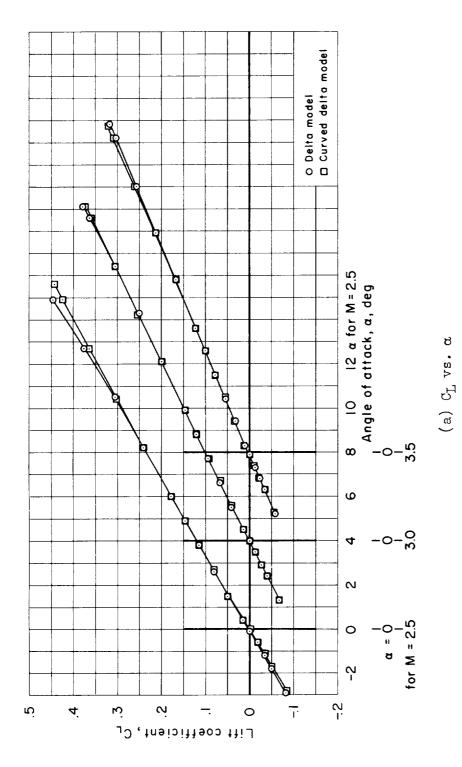


Figure 8.- Supersonic aerodynamic characteristics for the delta and curved delta models (R/ft = 2,000,000).

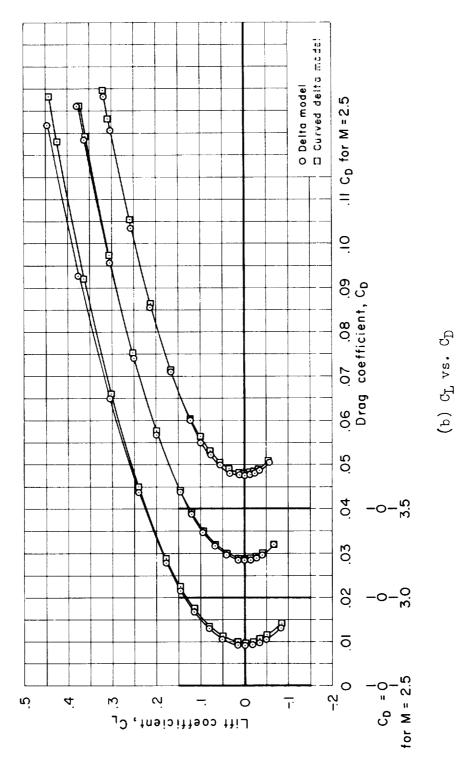
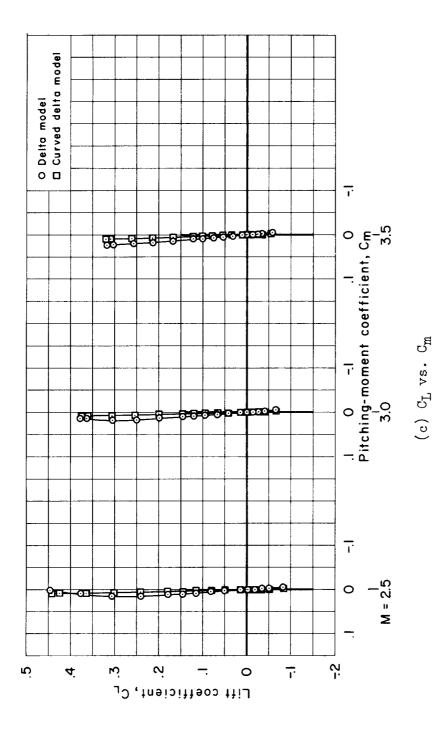
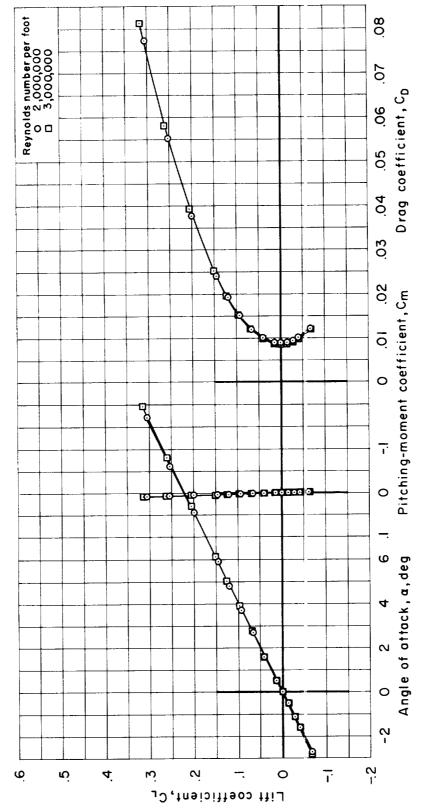


Figure 8.- Continued.

Figure 8.- Continued.





(d) Reynolds number effect at M = 3.00; curved delta model.

Figure 8.- Concluded.

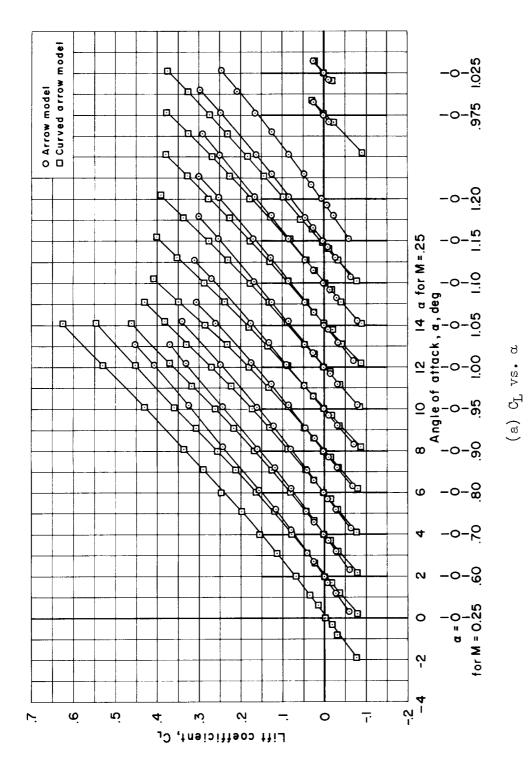


Figure 9.- Transonic aerodynamic characteristics for the arrow and curved arrow models (R/ft = 1,800,000 to 4,000,000).

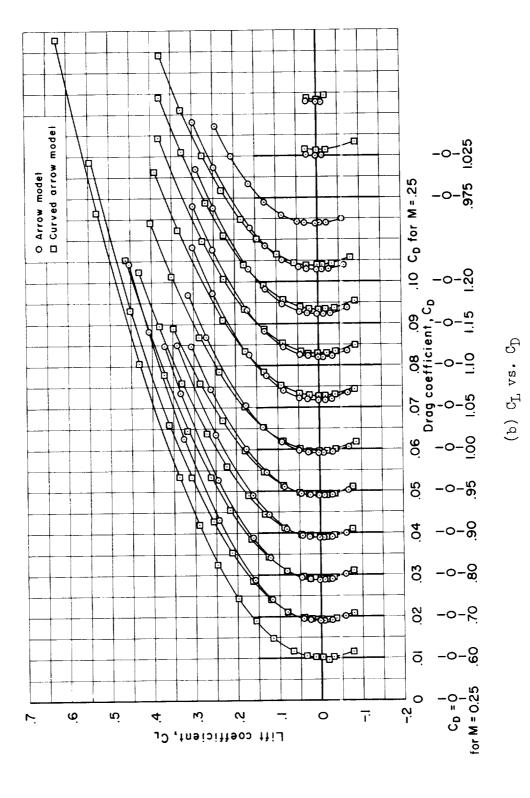


Figure 9.- Continued.

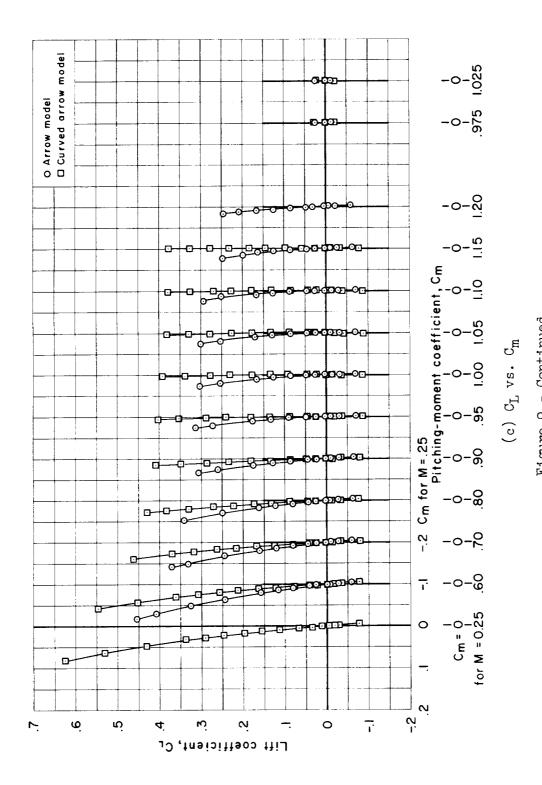
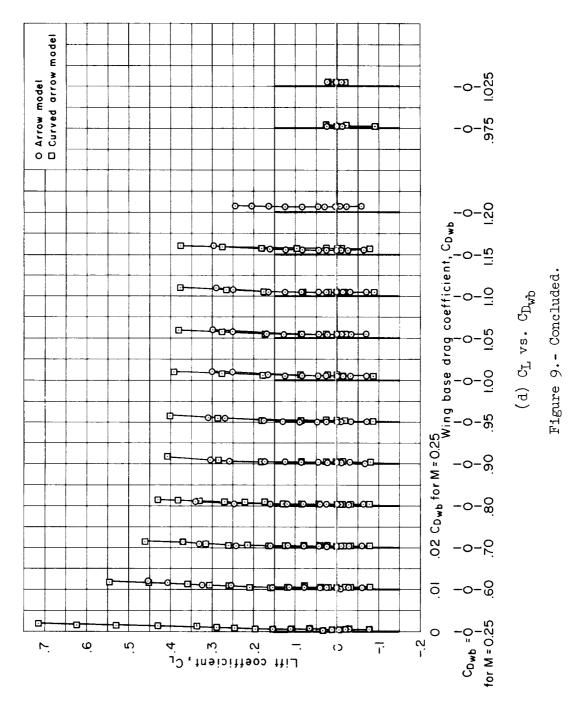


Figure 9.- Continued.



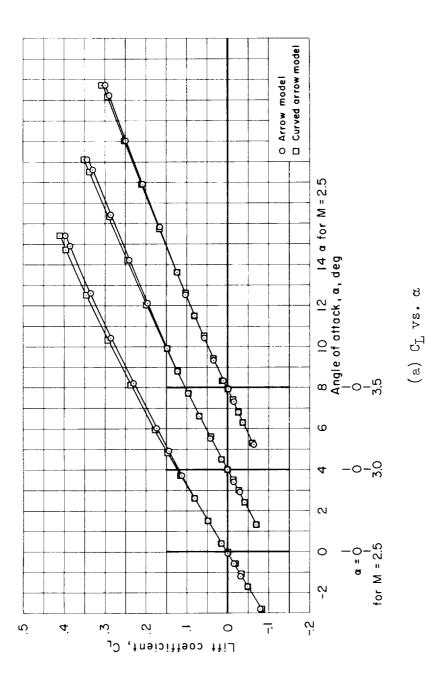


Figure 10.- Supersonic aerodynamic characteristics for the arrow and curved arrow models (R/ft = 2,000,000).

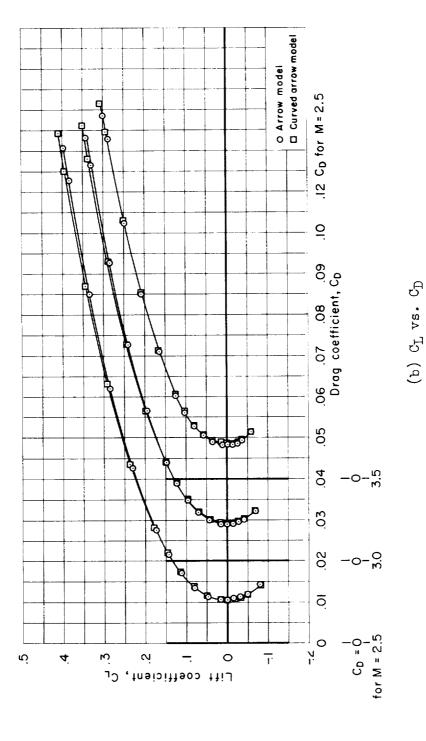
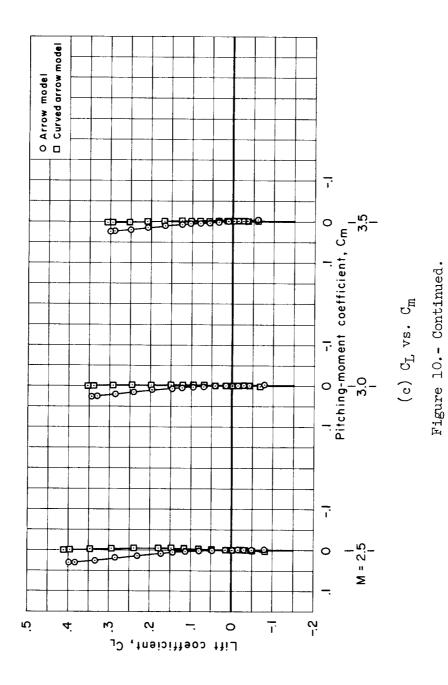
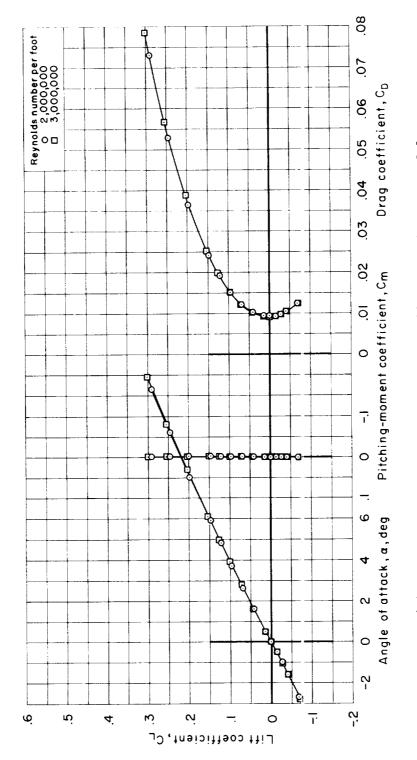


Figure 10.- Continued.





(d) Reynolds number effect at M = 3.00; curved arrow model.

Figure 10.- Concluded.

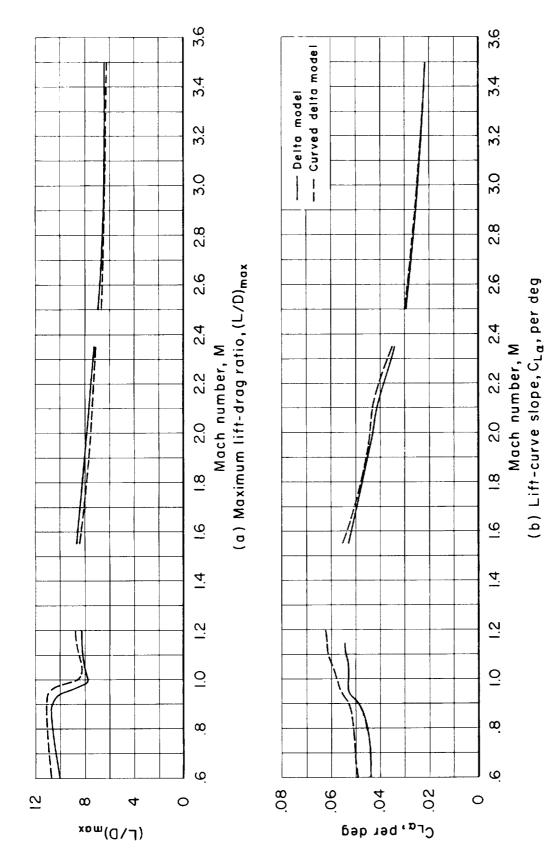


Figure 11. - Experimental aerodynamic trends with Mach number for the delta and curved delta models; transition fixed.

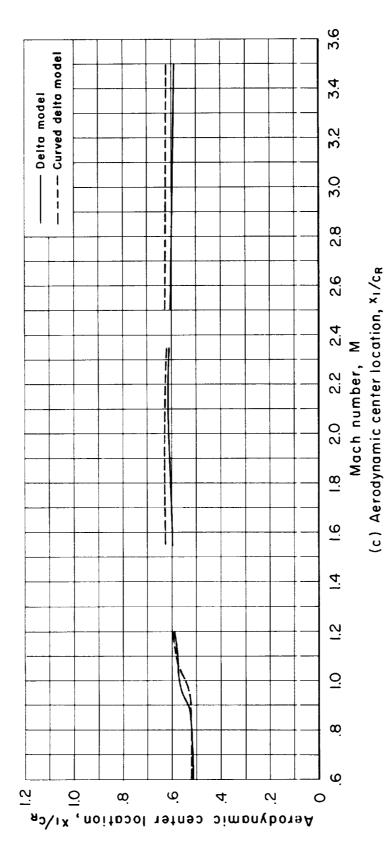


Figure 11. - Concluded.

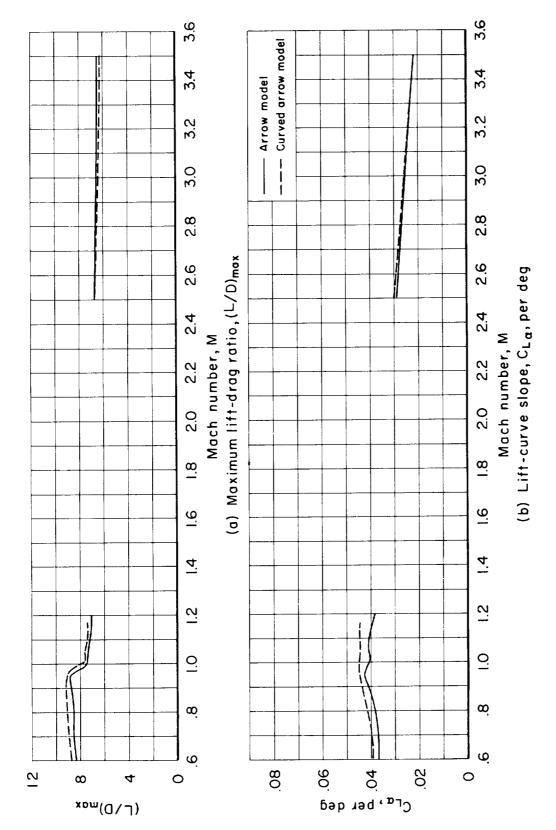


Figure 12.- Experimental aerodynamic trends with Mach number for the arrow and curved arrow models; transition fixed.

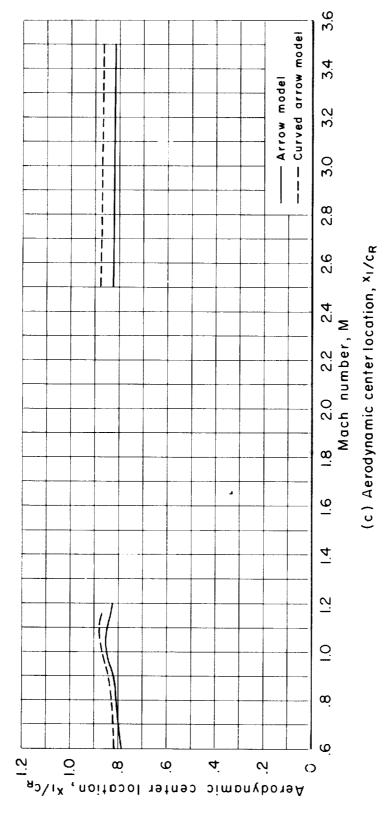


Figure 12.- Concluded.

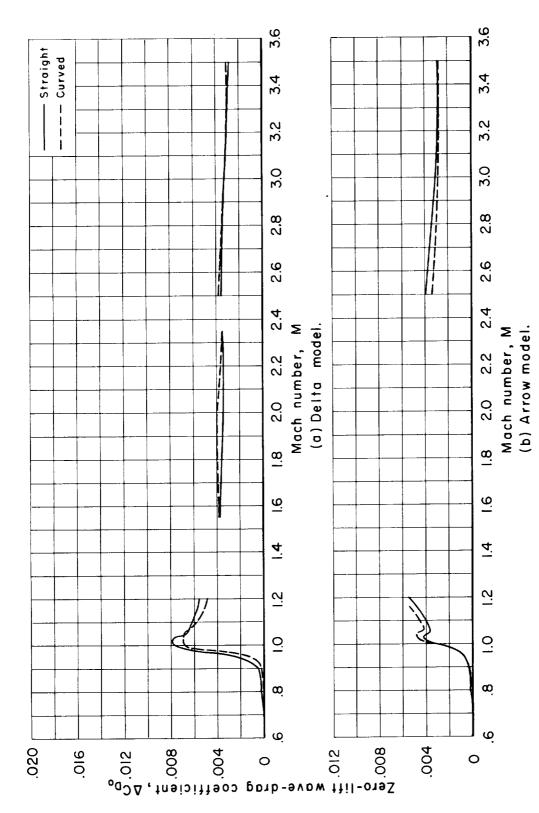


Figure 13. - Experimental zero-lift wave-drag coefficients of the straight and curved models.

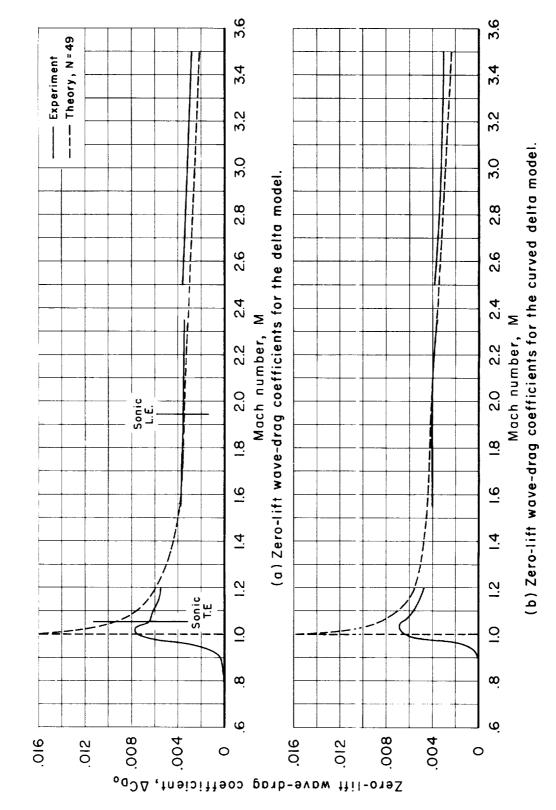


Figure 14.- Zero-lift wave-drag coefficients of the delta and curved delta models as determined by experiment and theory.

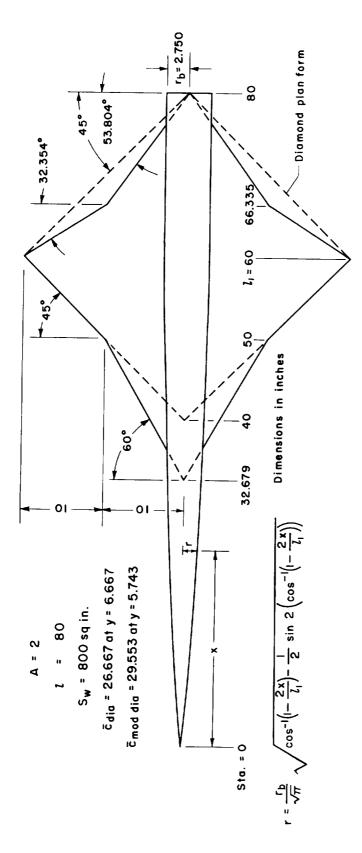


Figure 15.- Hypothetical models (diamond and modified diamond) selected to demonstrate potential wave-drag improvements.

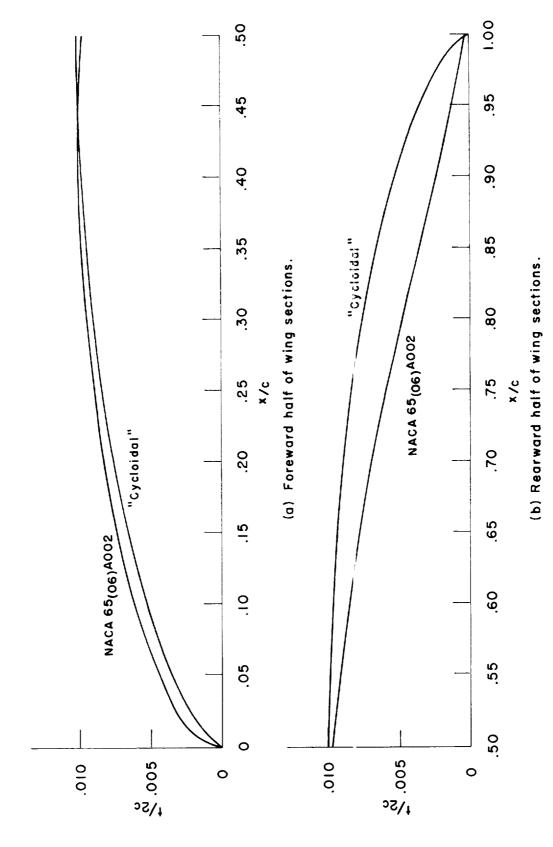
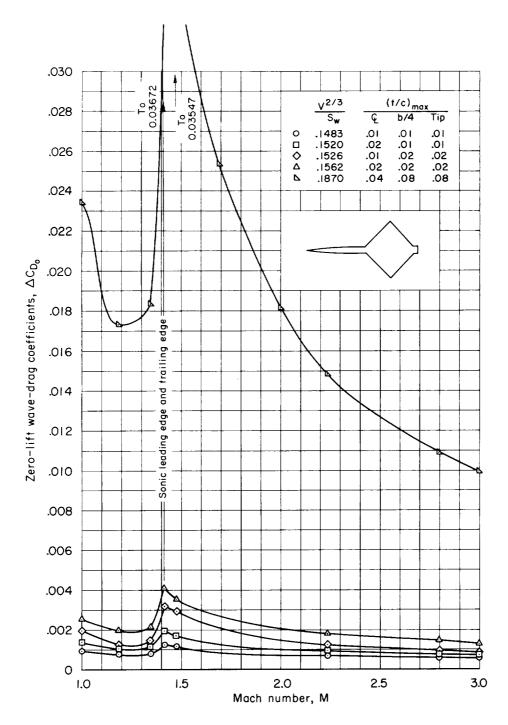
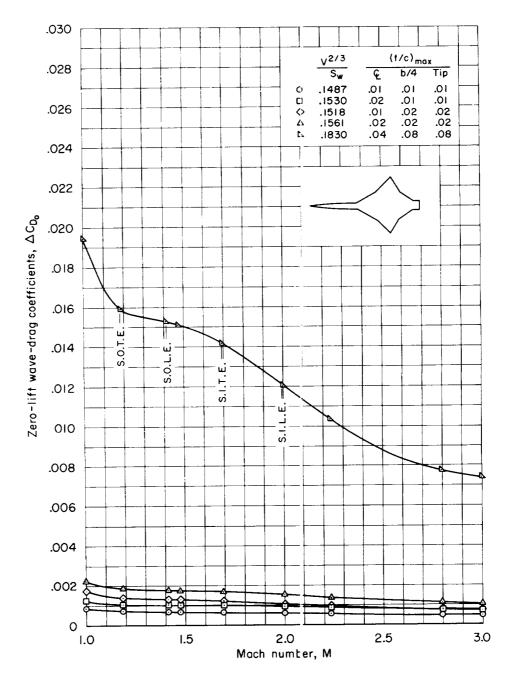


Figure 16.- The "cycloidal" and NACA 65(06)A002 wing sections.



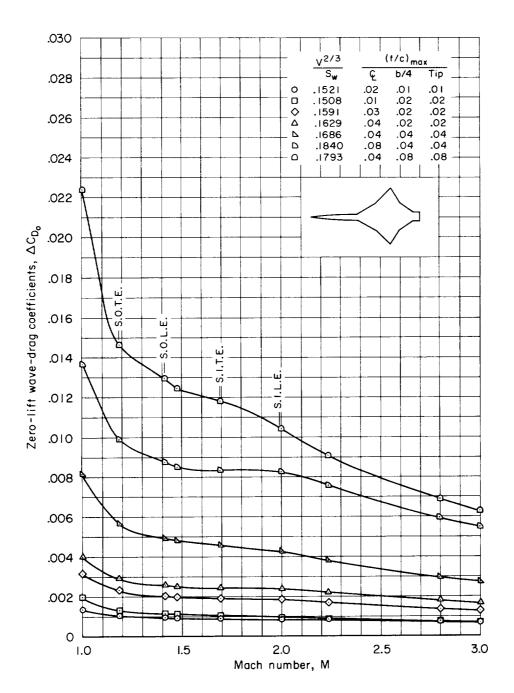
(a) Diamond model with "cycloidal" sections

Figure 17.- Theoretical zero-lift wave-drag coefficients for the hypothetical models with various wing section shapes and thickness (N=49).



(b) Modified diamond model with "cycloidal" sections.

Figure 17.- Continued.



(c) Modified diamond model with 65(06)A00X sections.

Figure 17.- Concluded.

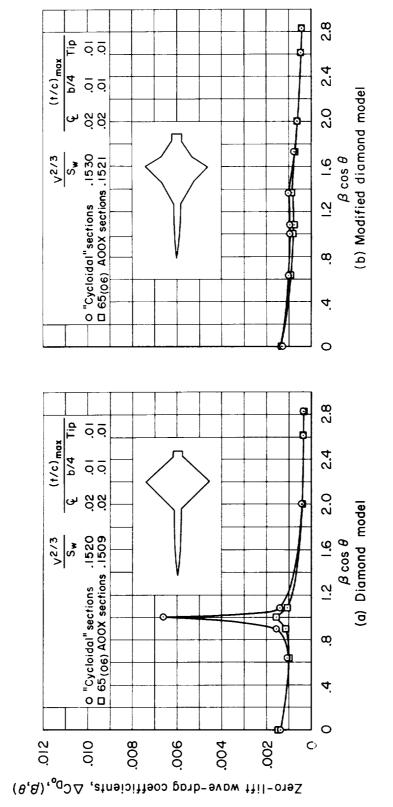


Figure 18.- Theoretical zero-lift wave-drag parameters determined as a function of  $\beta$  cos  $\theta$  for the hypothetical models with thin wing sections (N=49).

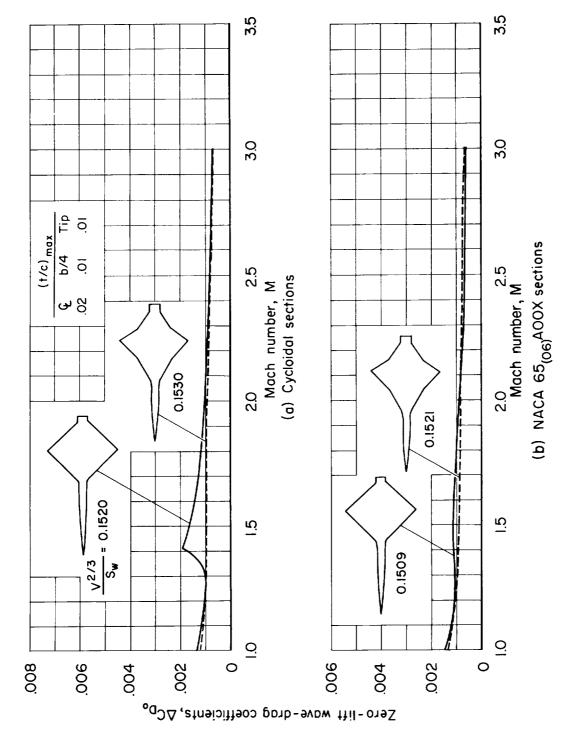


Figure 19.- Theoretical zero-lift wave-drag coefficients for the hypothetical models with thin wing sections (N= $^4$ 9).

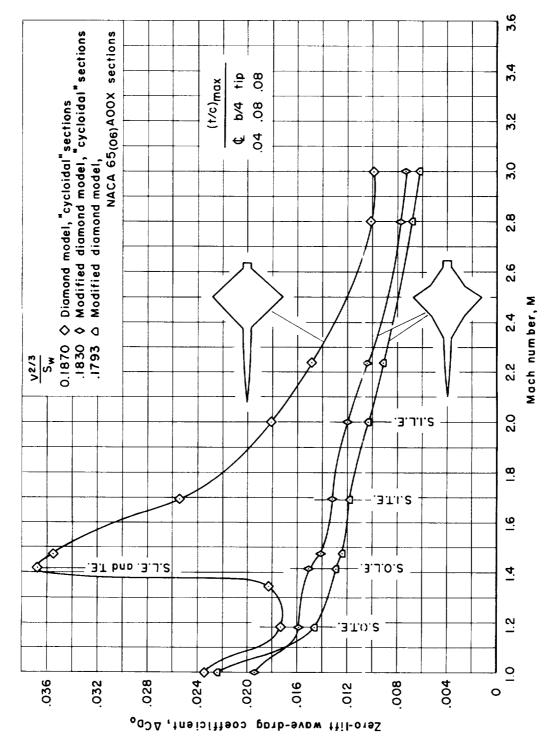


Figure 20.- Theoretical zero-lift wave-drag coefficients for the hypothetical models with thick wing sections (N= $\mu$ 9).

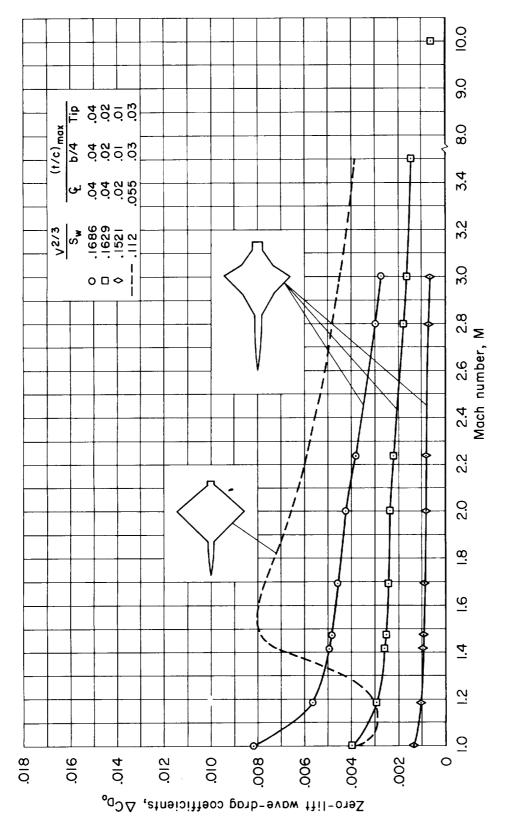


Figure 21. - Theoretical zero-lift wave-drag coefficients for the hypothetical modifieddiamond model with several wing thicknesses and for the blended diamond wing-body combination (N=49).

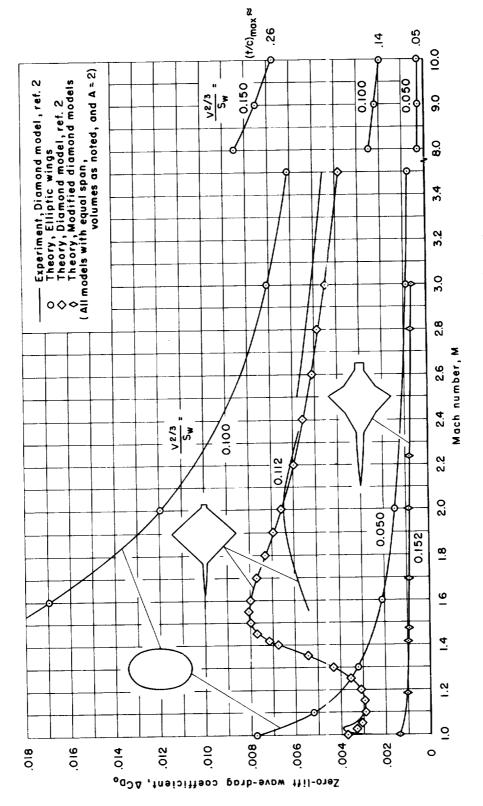


Figure 22.- Theoretical zero-lift wave-drag coefficients (N=49) for the hypothetical modified-diamond model, blended diamond model, and elliptic wings of comparable volume compared with experimental results from reference 2.

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Copies obtainable from NASA, Washington	NASA TM X-379  National Aeronautics and Space Administration. EVALUATION OF BLENDED WING-BODY COMBI- EVALUATION OF BLENDED WING-BODY COMBI- NATIONS WITH CURVED PLAN FORMS AT MACH NUMBERS UP TO 3.50. George H. Holdaway and Jack A. Mellenthin. October 1960. 66p.  (NASA TECHNICAL MEMORANDUM X-379)  (NASA TECHNICAL MEMORANDUM X-379)  Aerodynamic data are presented for aspect-ratio-2 delta and arrow plan forms with curved leading and trailing edges. The leading-edge sweeps of compa- rable and previously tested straight-edged wings were 59.04° and 70.82°, respectively. The corre- sponding trailing-edge sweeps were -18.43° and 41.19°. The curved leading and trailing edges had the same average sweep as the straight edges. A modi- fication to a diamond plan form which appears advan- tageous is discussed in an appendix.	Copies obtainable from NASA, Washington	NASA TM X-379  National Aeromantics and Space Administration. EVALUATION OF BLENDED WING-BODY COMBI- NATIONS WITH CURVED PLAN FORMS AT MACH NUMBERS UP TO 3.50. George H. Holdaway and Jack A. Mellenthin. October 1960. 66p. (NASA TECHNICAL MEMORANDUM X-379)  (NASA TECHNICAL MEMORANDUM X-379)  Aerodynamic data are presented for aspect-ratio-2 delta and arrow plan forms with curved leading and trailing edges. The leading-edge sweeps of compa- rable and previously tested straight-edged wings were 59.04° and 70.82°, respectively. The corre- sponding trailing-edge sweeps were -18.43 and 41.19°. The curved leading and trailing edges had the same average sweep as the straight edges. A modi- fication to a diamond plan form which appears advan- tageous is discussed in an appendix.
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